

Soft Bodies

using
Nvidia Flex

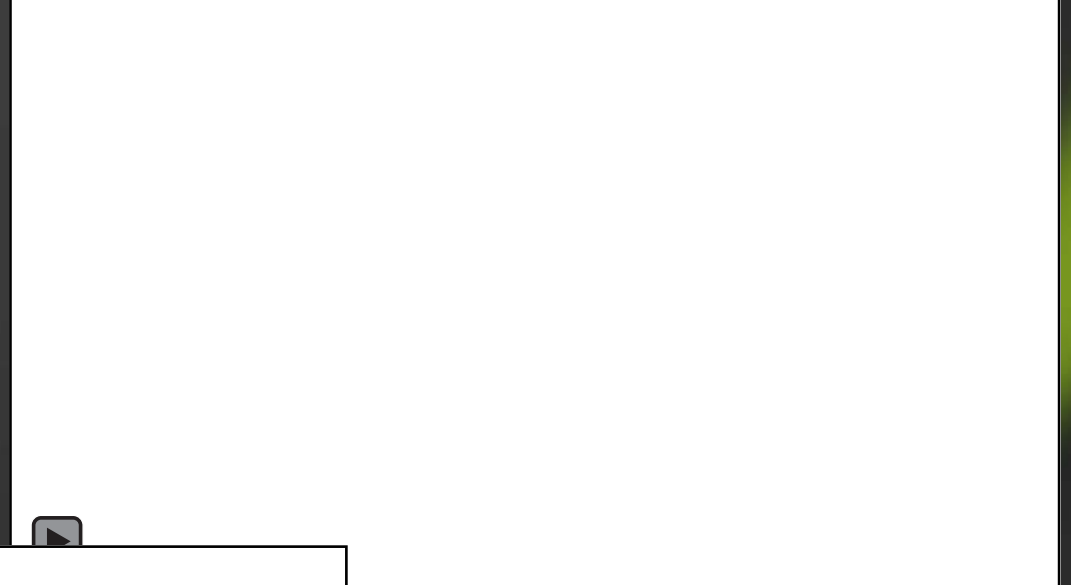
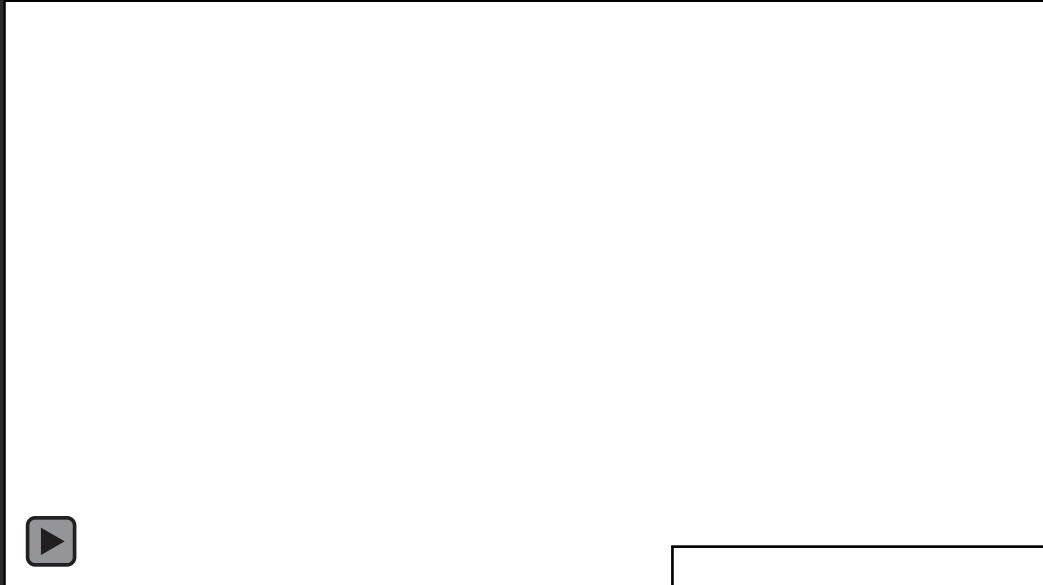
Simon Coenen

Demo video



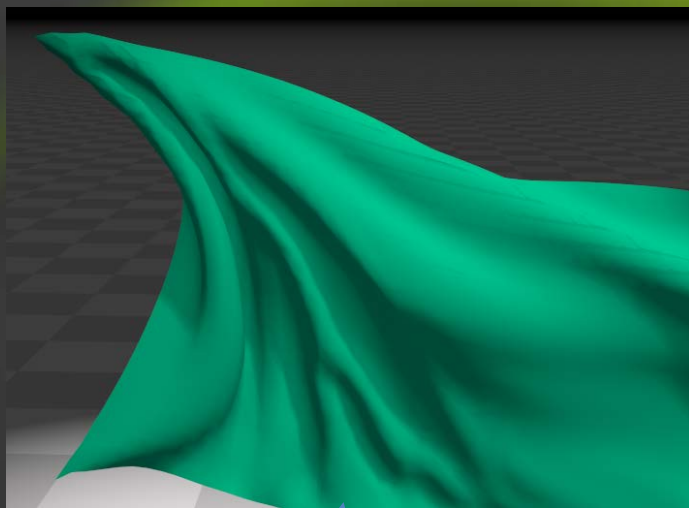
Nvidia FleX

Particle-based simulation library





Fluids



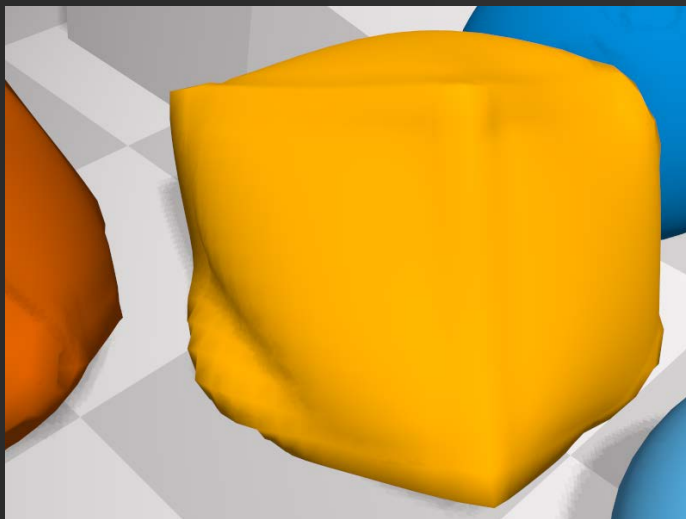
Cloth



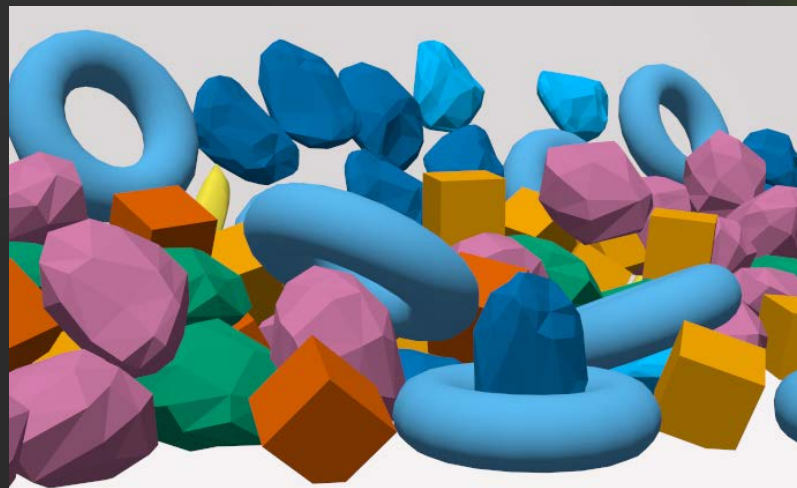
Gases

NVIDIA FLEX

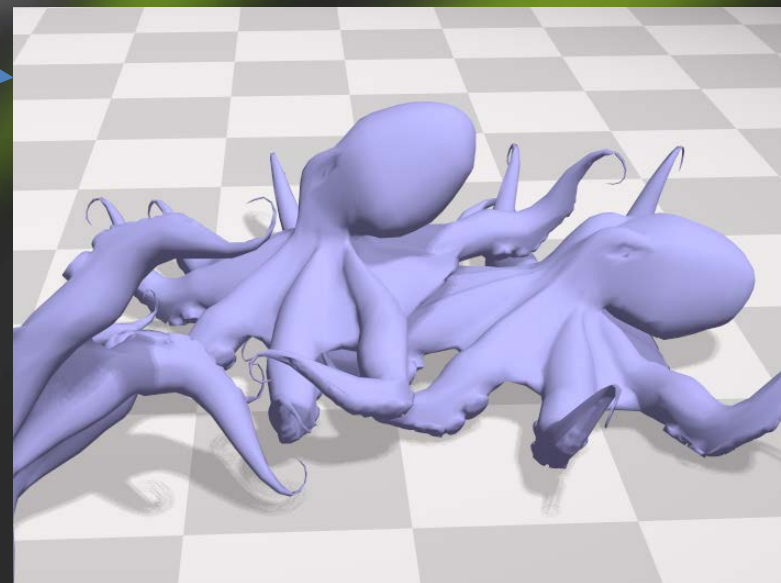
Inflatables



Rigidbodies



Softbodies

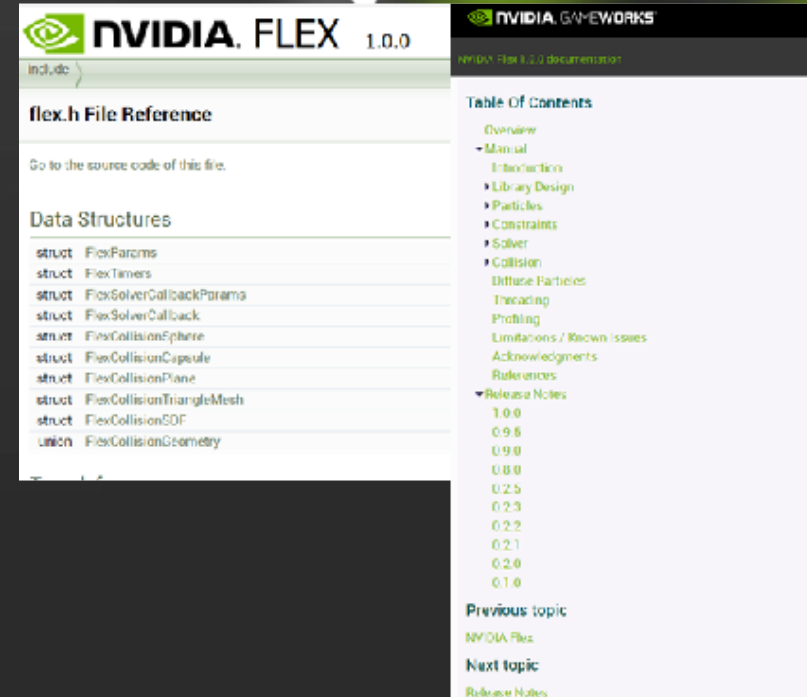
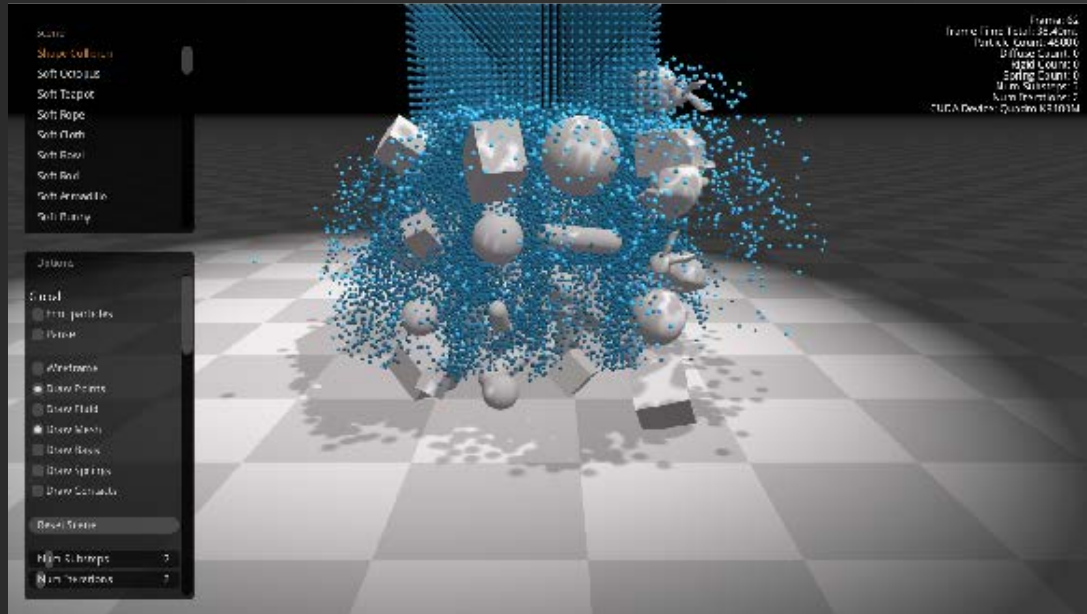


The SDK

DEMO +
SOURCE CODE

bin
core
data
demo
doc
extensions
external
include
lib
readme.txt
release_notes.txt

MANUAL +
CODE REFERENCE



Research: Soft bodies in Nvidia FleX

Starring...
Patrick "Star"

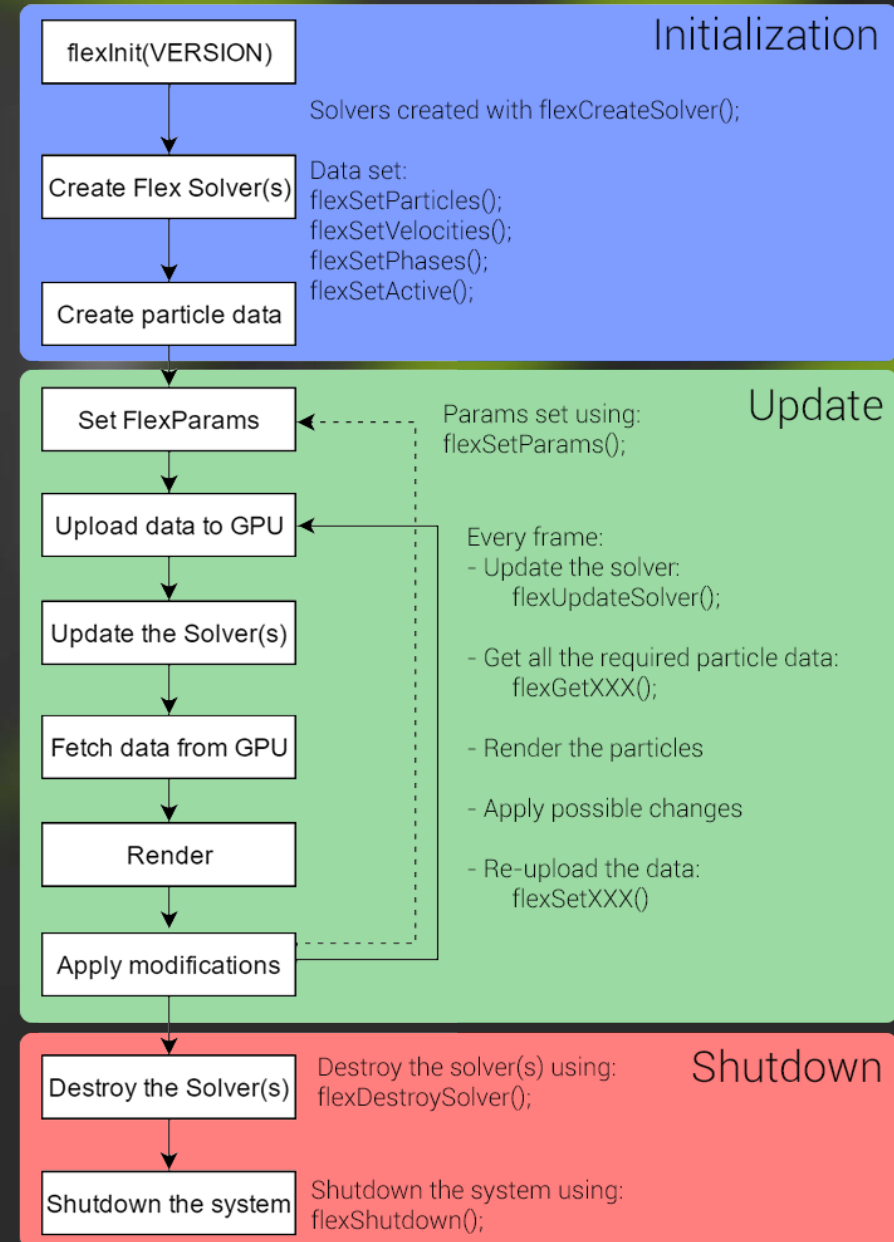
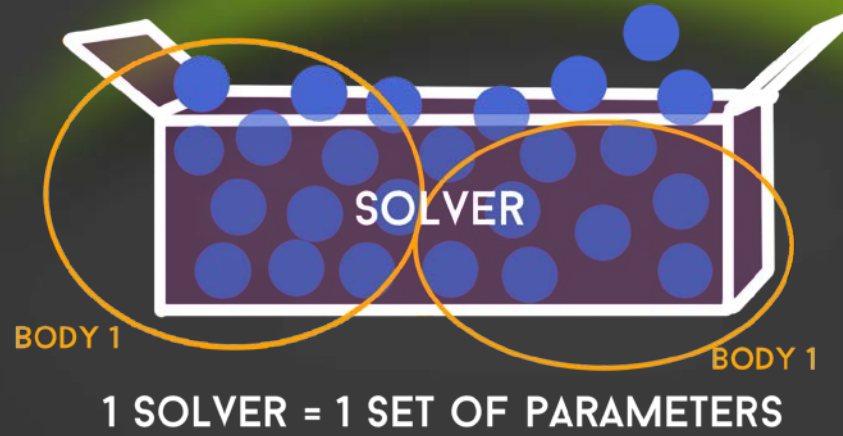


Main question:

How do I get from any regular mesh to a fully dynamic soft body?

Flex Solver

Solver =
Container that
does physics calculations



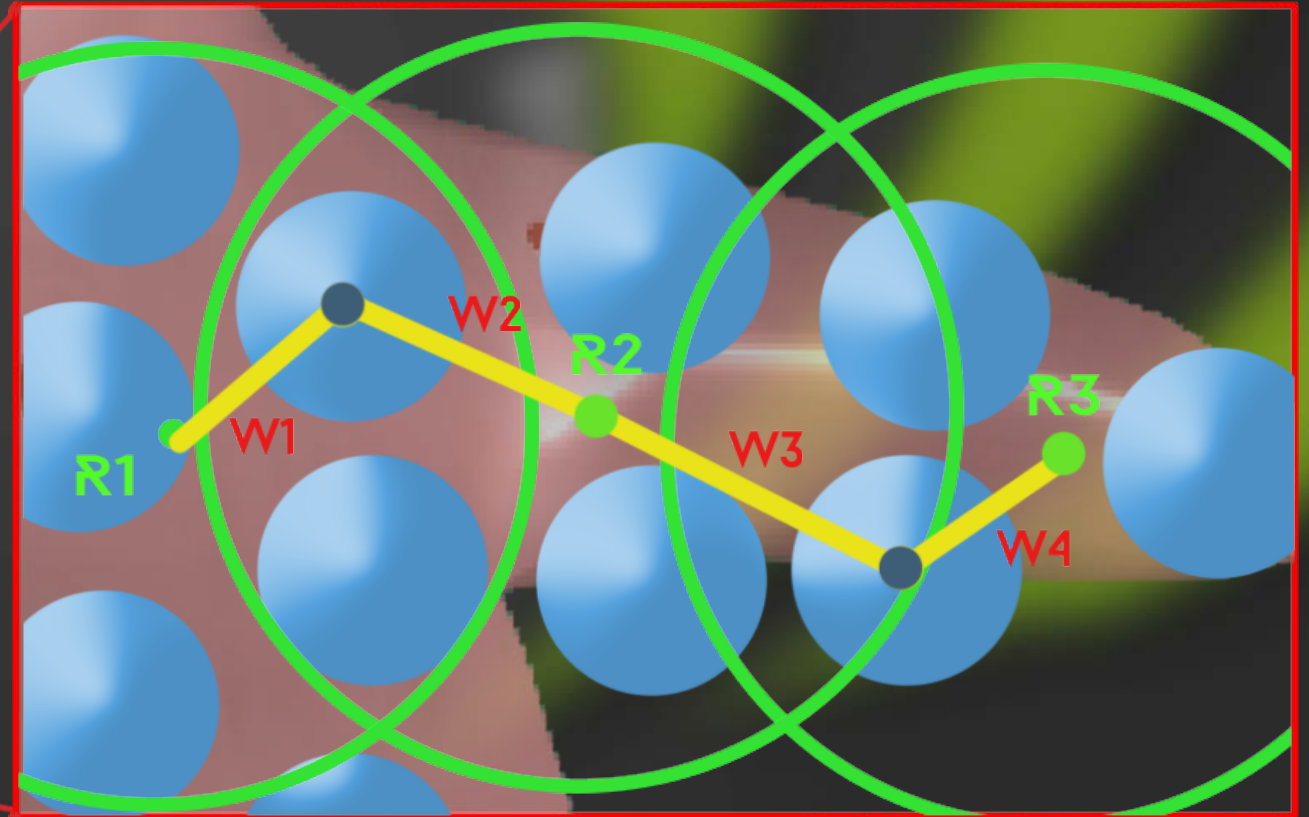
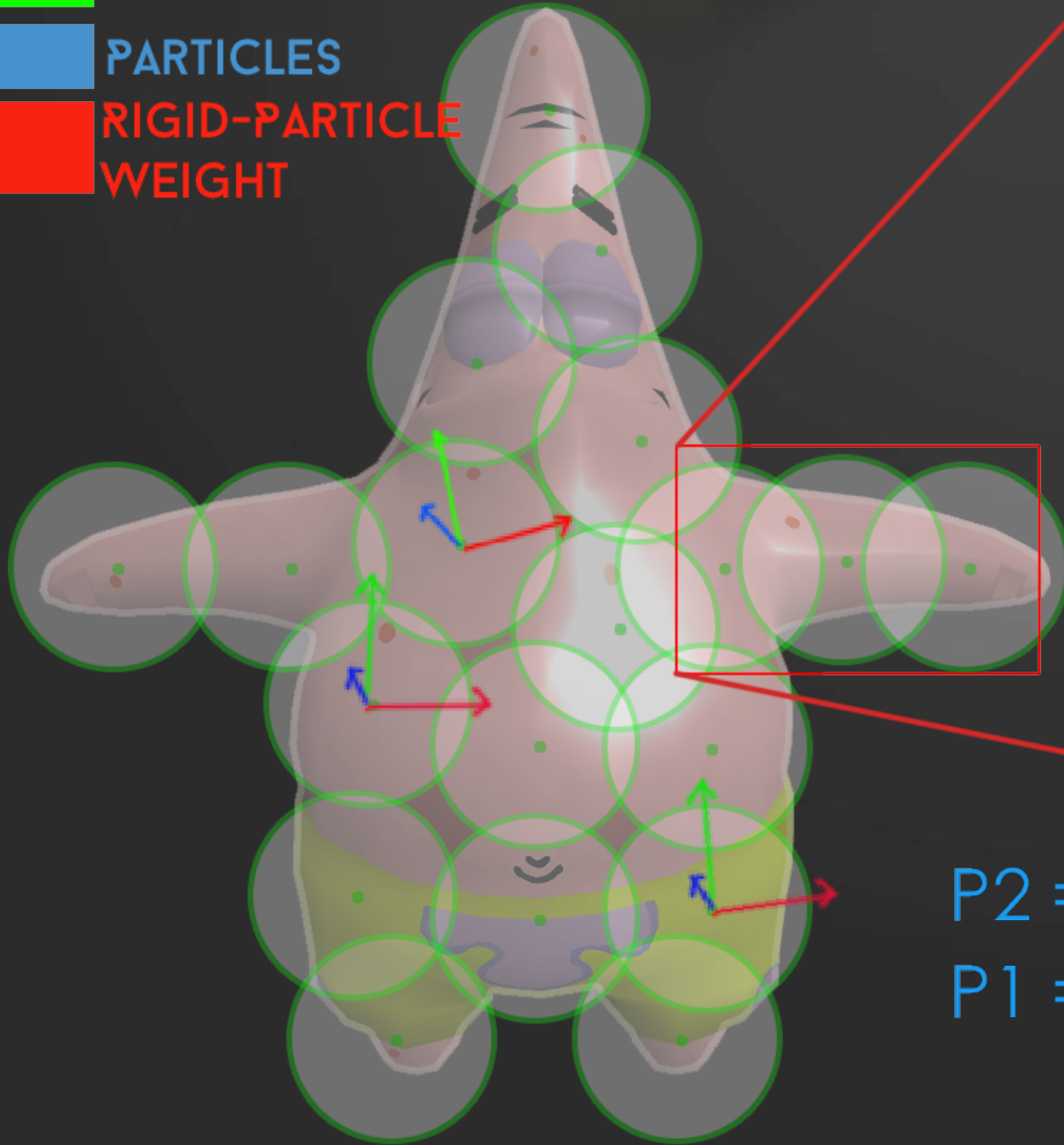
Particle → Cluster → Body

1 particle → 4 clusters

 RIGIDS

 PARTICLES

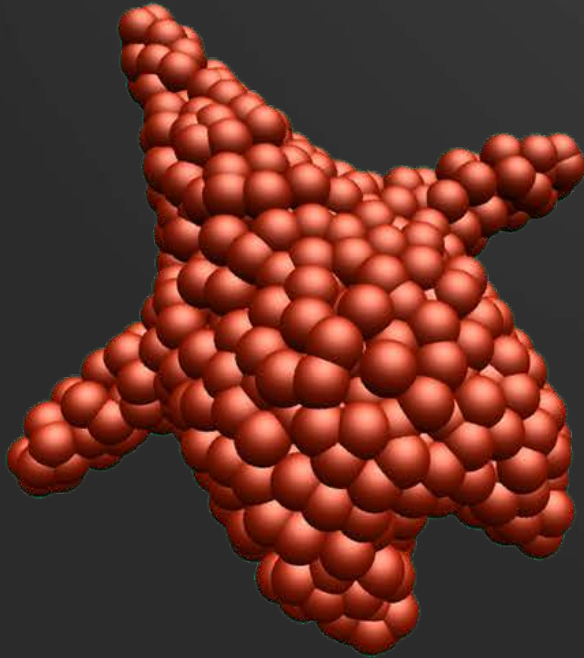
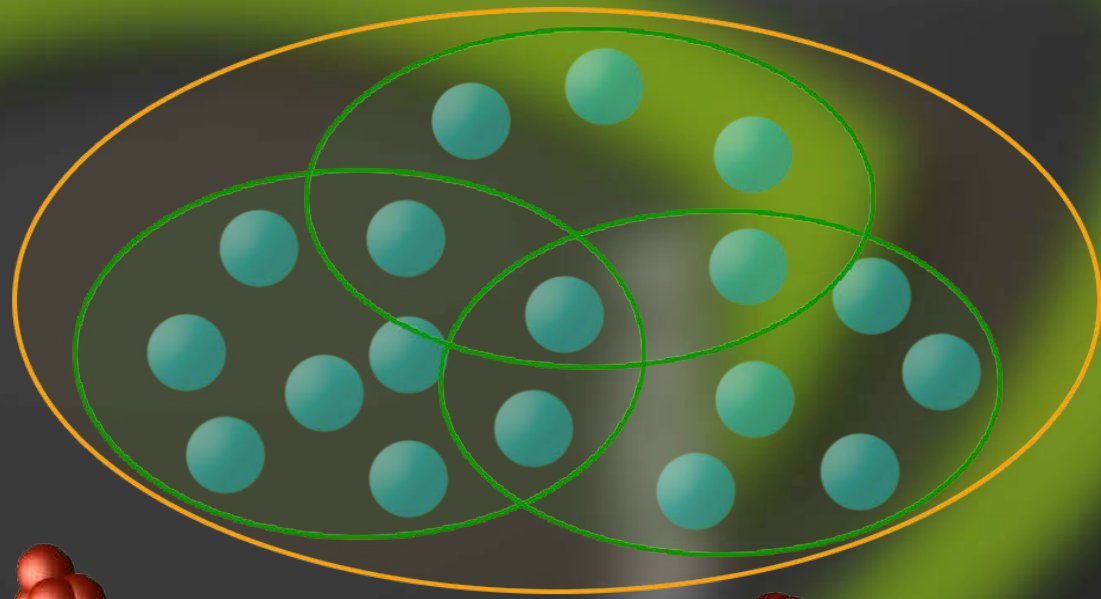
 RIGID-PARTICLE
WEIGHT



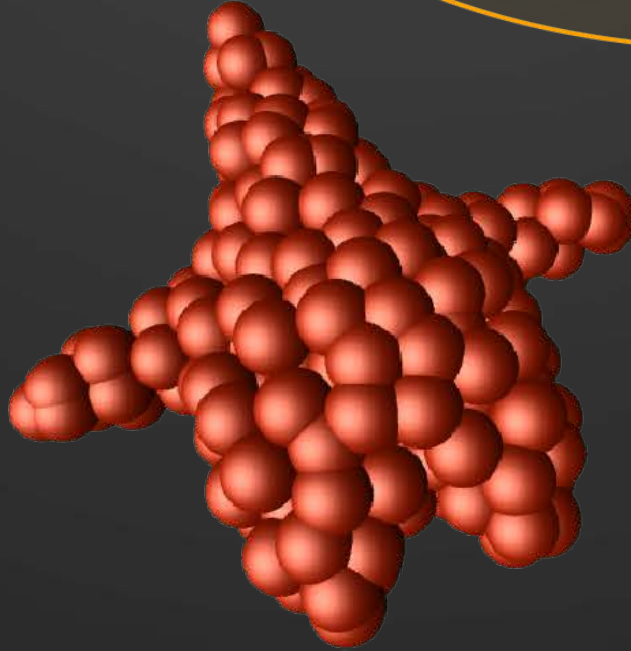
$$P2 = \text{weight1} * \text{Rigid1} + \text{weight2} * \text{Rigid2}$$

$$P1 = \text{weight3} * \text{Rigid2} + \text{weight4} * \text{Rigid3}$$

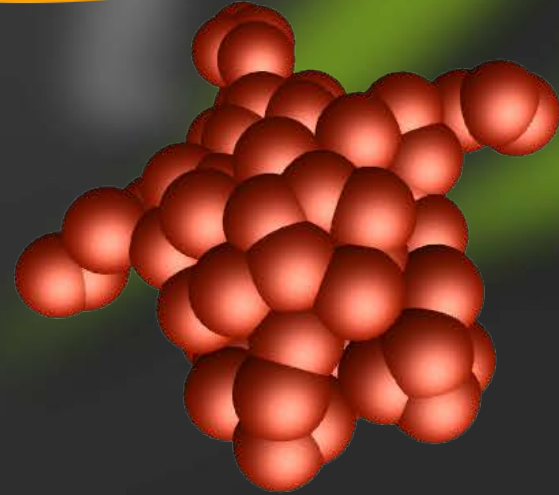
Soft bodies



-- Radius
-- ClusterRadius

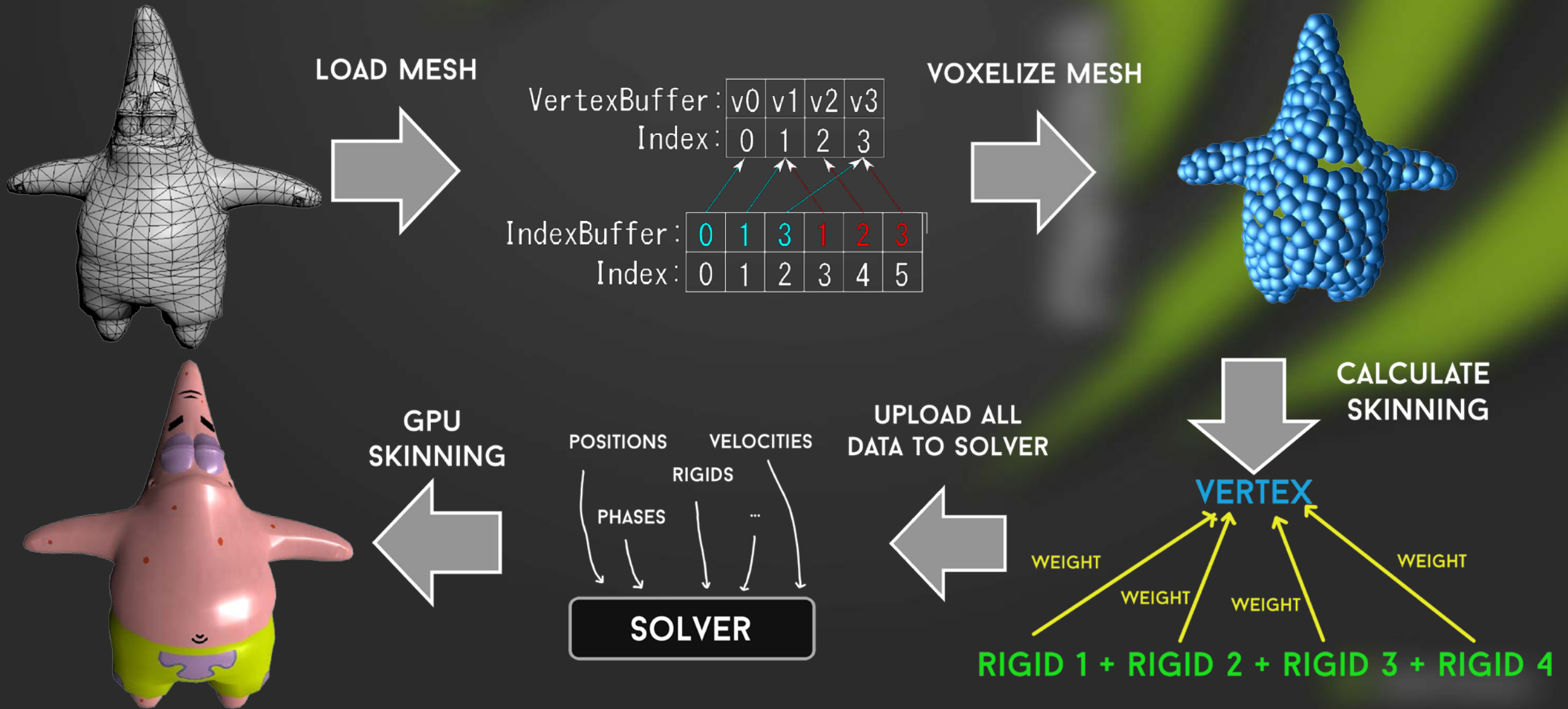


+ Radius
+ ClusterRadius



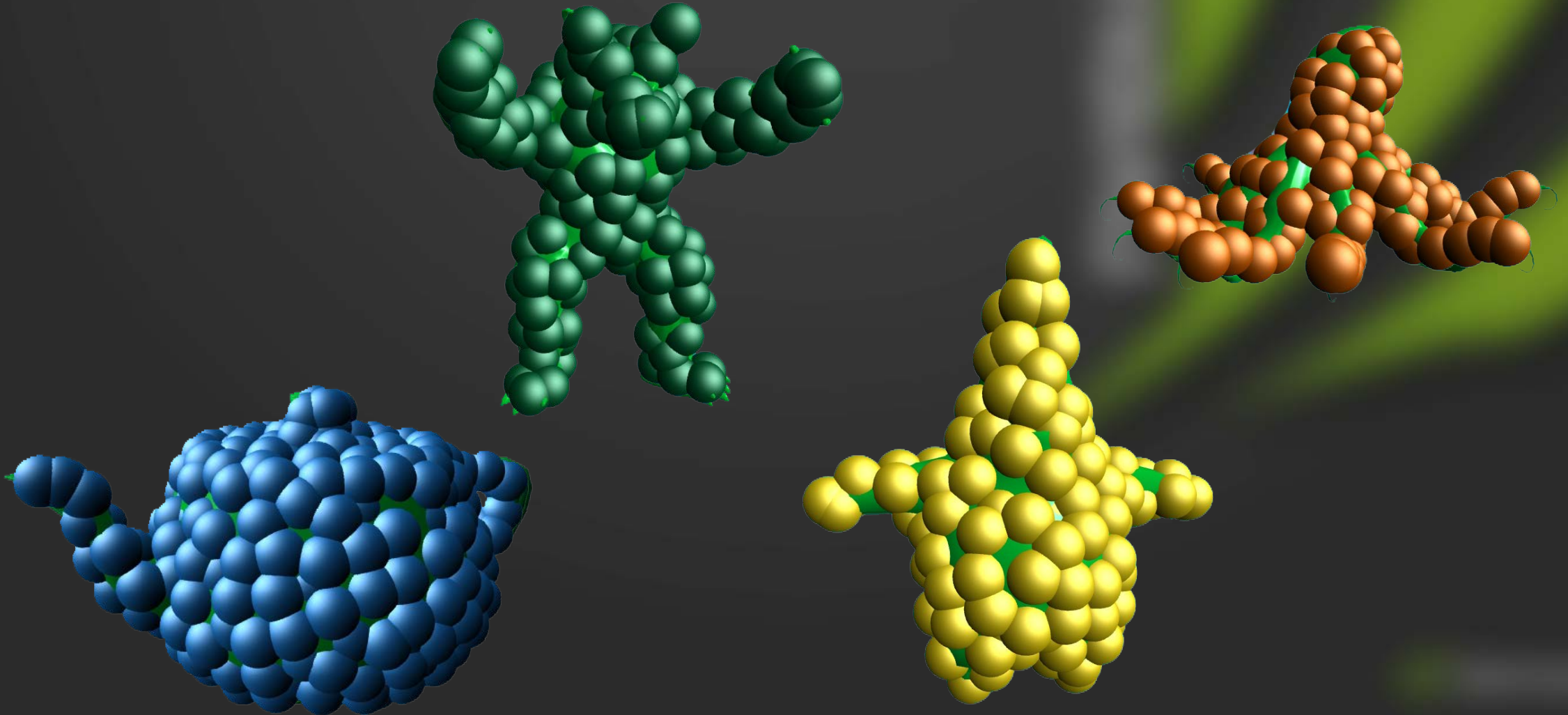
++ Radius
++ ClusterRadius

Creation



Quality vs. Quantity

↓ Radius == ↑ Quality == ↓ Performance



Quality vs. Quantity

↓ Radius == ↑ Quality == ↓ Performance

Stress testing

50 soft bodies

Radius = 0,15



Questions?



A more technical explanation can be read in the paper

Source

<https://bitbucket.org/simco50/d3dengine/src>

Portfolio

<http://www.simoncoenen.com>

